

**Warsaw University  
of Technology**



**Faculty of Power and  
Aeronautical Engineering**

WARSAW UNIVERSITY OF TECHNOLOGY

Institute of Aeronautics and Applied Mechanics

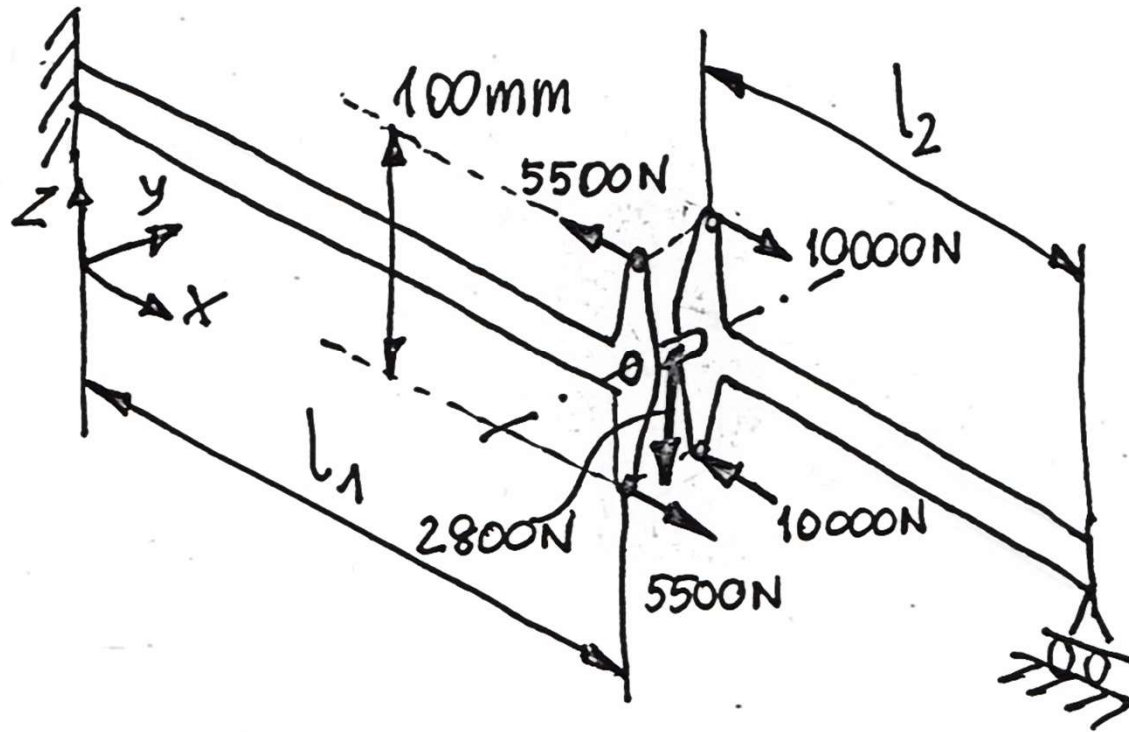
# Finite element method (FEM)

Beam with a hinge

05.2021

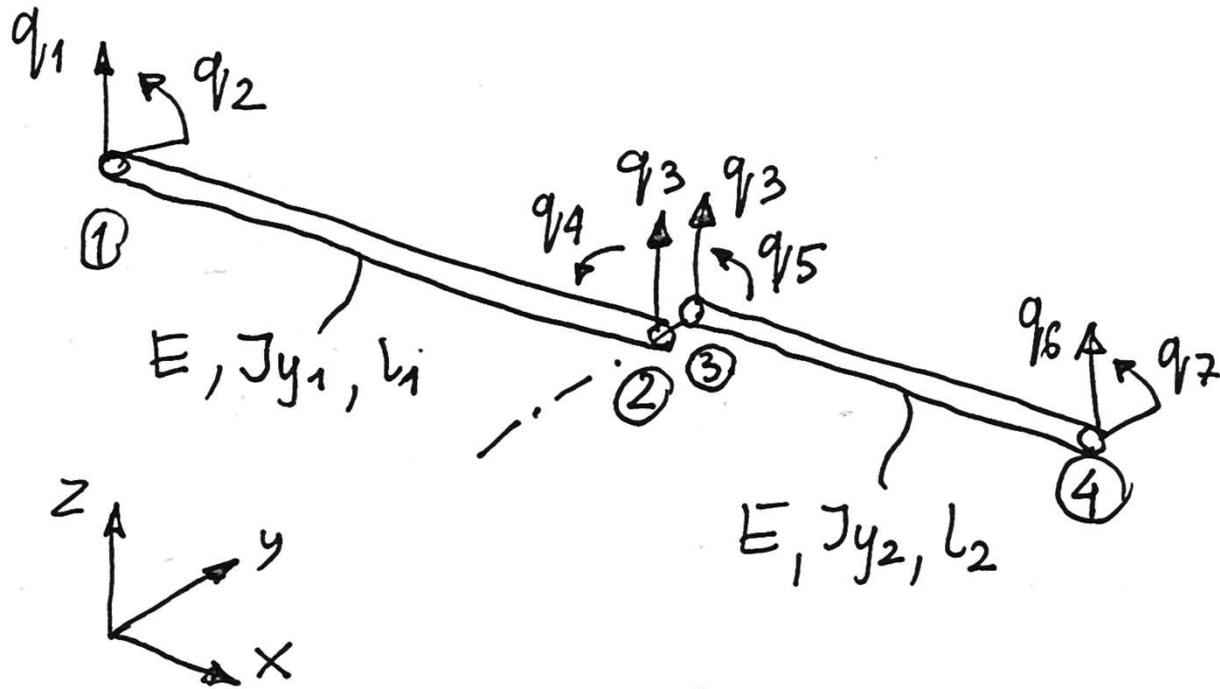
# EXAMPLE : BEAM WITH A HINGE

BUILD A FINITE ELEMENT MODEL. USE 2 FES.  
FIND UNKNOWN DISPLACEMENTS, DEFLECTION, REACTIONS,  
INTERNAL FORCES AND CHECK THE EQUILIBRIUM.



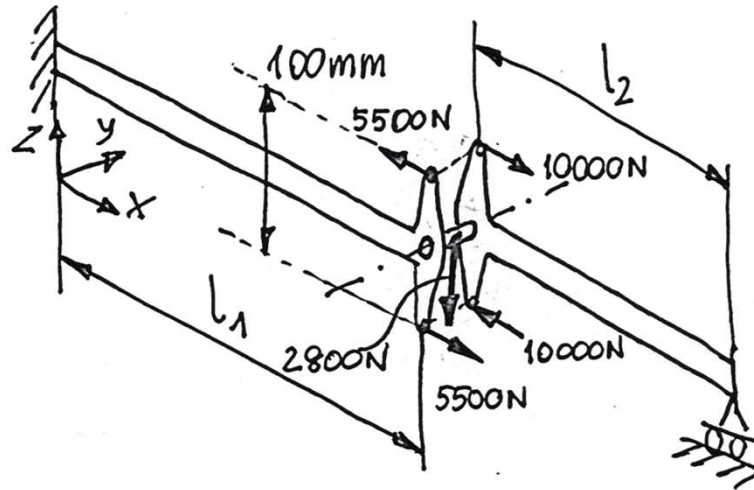
$$E = 2 \cdot 10^5 \text{ MPa}$$
$$l_1 = 1000 \text{ mm}$$
$$l_2 = 500 \text{ mm}$$
$$J_{y_1} = 1.143 \cdot 10^5 \text{ mm}^4$$
$$J_{y_2} = 1.621 \cdot 10^5 \text{ mm}^4$$

# NODAL PARAMETERS



$$\underset{1 \times 7}{Lq} = Lq_1, q_2, q_3, q_4, q_5, q_6, q_7$$

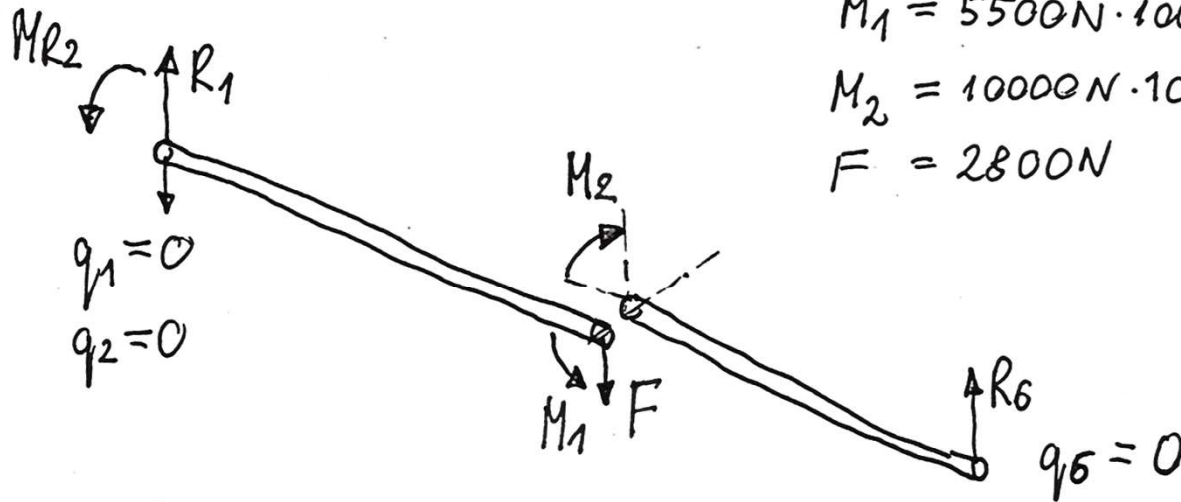
# LOADS AND REACTIONS



$$M_1 = 5500\text{N} \cdot 100\text{mm} = 0.55 \cdot 10^6 \text{ Nmm}$$

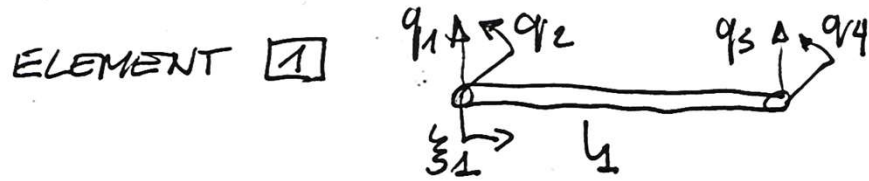
$$M_2 = 10000\text{N} \cdot 100\text{mm} = 1 \cdot 10^6 \text{ Nmm}$$

$$F = 2800\text{N}$$



$$LF|_{1 \times 7} = [R_1, M_{R2}, -F, M_1, -M_2, R_6, 0]$$

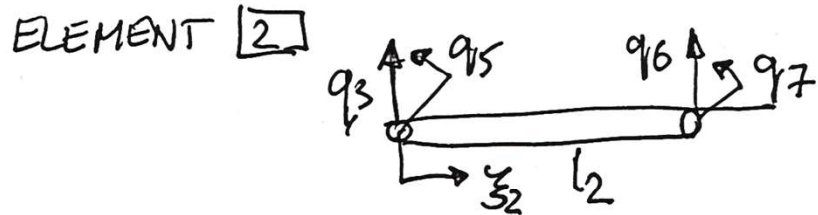
# STIFFNESS MATRICES



$$[K]_1 = \frac{2EJy_1}{l_1^3} \begin{bmatrix} 6 & 3l_1 & -6 & 3l_1 \\ 3l_1 & 2l_1^2 & -3l_1 & l_1^2 \\ -6 & -3l_1 & 6 & -3l_1 \\ 3l_1 & l_1^2 & -3l_1 & 2l_1^2 \end{bmatrix} ;$$

$$[K]^*_1 = \begin{bmatrix} \text{shaded } [K]_1 & [0]_{4 \times 3} \\ [0]_{3 \times 4} & [0]_{3 \times 3} \end{bmatrix}$$

7x7



$$[K]_2 = \frac{2EJy_2}{l_2^3} \begin{bmatrix} 6 & 3l_2 & -6 & 3l_2 \\ 3l_2 & 2l_2^2 & -3l_2 & l_2^2 \\ -6 & -3l_2 & 6 & -3l_2 \\ 3l_2 & l_2^2 & -3l_2 & 2l_2^2 \end{bmatrix} ;$$

$$[K]^*_2 = \begin{bmatrix} 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & \text{shaded } [K]_2 & 0 & \text{shaded } [K]_2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & \text{shaded } [K]_2 & 0 & \text{shaded } [K]_2 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

7x7

# GLOBAL STIFFNESS MATRIX

$$[K]_{7 \times 7} = [K]_1^* + [K]_2^* =$$

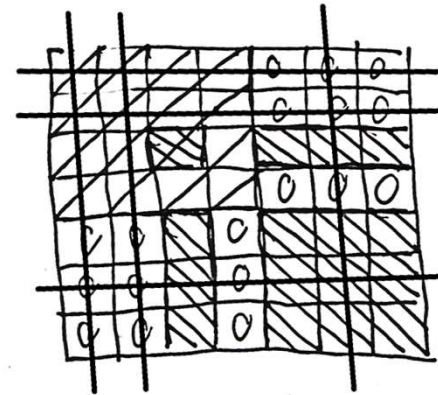
				0	0	0
				0	0	0
				0	0	0
0	0		0			
0	0		0			
0	0		0			

BOUNDARY CONDITIONS :

$$q_1 = 0, q_2 = 0, q_6 = 0 \Rightarrow N = \text{NDOF} - \text{DOF} = 4$$

$$\underbrace{\begin{bmatrix} \text{shaded} & \text{shaded} & 0 & 0 \\ \text{shaded} & 0 & \text{shaded} & \text{shaded} \\ \text{shaded} & 0 & \text{shaded} & \text{shaded} \\ \text{shaded} & \text{shaded} & \text{shaded} & \text{shaded} \end{bmatrix}}_{[K]} \cdot \begin{Bmatrix} q_3 \\ q_4 \\ q_5 \\ q_7 \end{Bmatrix} = \begin{Bmatrix} -F \\ M_1 \\ -M_2 \\ 0 \end{Bmatrix}$$

$[K]$   
4x4





$$[K]_{4 \times 4} = \begin{bmatrix} \frac{12EJy_1}{l_1^3} + \frac{12EJy_2}{l_2^3} & -\frac{6EJy_1}{l_1^2} & \frac{6EJy_2}{l_2^2} & \frac{6EJy_2}{l_2^2} \\ -\frac{6EJy_1}{l_1^2} & \frac{4EJy_1}{l_1} & 0 & 0 \\ \frac{6EJy_2}{l_2^2} & 0 & \frac{4EJy_2}{l_2} & \frac{2EJy_2}{l_2} \\ \frac{6EJy_2}{l_2^2} & 0 & \frac{2EJy_2}{l_2} & \frac{4EJy_2}{l_2} \end{bmatrix}$$

$$a = \frac{12EJy_1}{l_1^3} + \frac{12EJy_2}{l_2^3}$$

$$b = -\frac{6EJy_1}{l_1^2}, \quad c = \frac{6EJy_2}{l_2^2}$$

$$d = \frac{4EJy_1}{l_1}, \quad f = \frac{4EJy_2}{l_2}$$

$$[K]_{4 \times 4} = \begin{bmatrix} a & b & c & c \\ b & d & 0 & 0 \\ c & 0 & f & f/2 \\ c & 0 & f/2 & f \end{bmatrix}$$



$$\begin{cases} a q_3 + b q_4 + c q_5 + c q_7 = -F \\ b q_3 + d q_4 = M_1 \\ c q_3 + f q_5 + \frac{f}{2} q_7 = -M_2 \\ c q_3 + \frac{f}{2} q_5 + f \cdot q_7 = 0 \end{cases}$$

$$\begin{cases} \text{III} - \text{IV} : \frac{f}{2} q_5 - \frac{f}{2} q_7 = -M_2 \Rightarrow q_5 = q_7 - \frac{2M_2}{f} \\ \text{III} : c q_3 + f \left( q_7 - \frac{2M_2}{f} \right) + \frac{f}{2} q_7 = -M_2 \\ c q_3 + \frac{3}{2} f \cdot q_7 = M_2 \Rightarrow q_7 = \frac{2(M_2 - c q_3)}{3f} \\ \text{II} : q_4 = \frac{M_1 - b q_3}{d} \\ q_5 = \frac{2(M_2 - c q_3)}{3f} - \frac{2M_2}{f} = -\frac{4M_2 + 2c q_3}{3f} \end{cases}$$

I:

$$a \cdot q_3 + b \left( \frac{M_1 - b q_3}{d} \right) - c \cdot \frac{4M_2 + 2c q_3}{3f} + c \cdot \frac{2(M_2 - c q_3)}{3f} = -F$$

$$a \cdot q_3 + \frac{b}{d} M_1 - \frac{b^2}{d} q_3 - \frac{4M_2 c}{3f} - \frac{2c^2 q_3}{3f} + \frac{2M_2 c}{3f} - \frac{2c^2 q_3}{3f} = -F$$

$$\left( a - \frac{b^2}{d} - \frac{4c^2}{3f} \right) q_3 = -F - \frac{b}{d} M_1 + \frac{2c M_2}{3f}$$

$$q_3 = \frac{\frac{2c M_2}{3f} - F - \frac{b}{d} M_1}{\left( a - \frac{b^2}{d} - \frac{4c^2}{3f} \right)} = \frac{\frac{2 \cdot 6EJy_2 \cdot M_2 \cdot l_2}{3 \cdot l_2^2 \cdot 4EJy_2} - F + \frac{6EJy_1 \cdot M_1 \cdot l_1}{l_1^2 \cdot 4 \cdot EJy_1}}{\left( a - \frac{b^2}{d} - \frac{4c^2}{3f} \right)}$$

$$a - \frac{b^2}{d} - \frac{4c^2}{3f} = \frac{12EJy_1}{l_1^3} + \frac{12EJy_2}{l_2^3} - \frac{36E^2 Jy_1^2 \cdot l_1}{l_1^4 \cdot 4EJy_1} - \frac{4 \cdot 36E^2 Jy_2^2 \cdot l_2}{3 \cdot l_2^4 \cdot 4EJy_2} = \frac{3EJy_1}{l_1^3}$$

$$q_3 = \frac{\left( \frac{3}{2} \frac{M_1}{l_1} + \frac{M_2}{l_2} - F \right) l_1^3}{3EJy_1}$$

## UNKNOWN NODAL PARAMETERS

$$q_3 = \frac{\left(\frac{3}{2} \frac{M_1}{l_1} + \frac{M_2}{l_2} - F\right) l_1^3}{3 E J y_2} = 0.3645 \text{ mm}$$

$$q_4 = \frac{\left(M_1 + \frac{M_2 l_1}{2 l_2} - \frac{F l_1}{2}\right) l_1}{E J y_1} = 6.5617 \cdot 10^{-3} = 0.38^\circ$$

$$q_5 = - \frac{M_2 l_2 + \frac{J y_2 l_1^3}{J y_1 l_2} \left(\frac{3}{2} \frac{M_1}{l_1} + \frac{M_2}{l_2} - F\right)}{3 E J y_2} = -5.8699 \cdot 10^{-3} = -0.34^\circ$$

$$q_7 = \frac{\frac{1}{2} M_2 l_2 - \frac{J y_2 l_1^3}{J y_1 l_2} \left(\frac{3}{2} \frac{M_1}{l_1} + \frac{M_2}{l_2} - F\right)}{3 E J y_2} = 1.8415 \cdot 10^{-3} = 0.11^\circ$$

REACTIONS:

$[K] =$   
7x7

				0	0	0
				0	0	0
				0	0	0
0	0		0			
0	0		0			
0	0		0			

$$R_1 = -\frac{12 EJy_1}{l_1^3} \cdot q_3 + \frac{6 EJy_1}{l_1^2} \cdot q_4 =$$

$$= -4 \left( \frac{3 M_1}{2 l_1} + \frac{M_2}{l_2} - F \right) + \frac{6}{l_1} \left( M_1 + \frac{M_2 l_1}{2 l_2} - \frac{F l_1}{2} \right) = F - \frac{M_2}{l_2} = 800 \text{ N}$$

$$M_{R2} = -\frac{6 EJy_1}{l_1^2} \cdot q_3 + \frac{2 EJy_1}{l_1} q_4$$

$$= -2 l_1 \left( \frac{3 M_1}{2 l_1} + \frac{M_2}{l_2} - F \right) + 2 \left( M_1 + \frac{M_2 l_1}{2 l_2} - \frac{F l_1}{2} \right) =$$

$$= -(3 M_1 + 2 \frac{M_2 l_1}{l_2} - 2 F l_1) + 2 M_1 + M_2 \frac{l_1}{l_2} - F l_1 =$$

$$= F l_1 - M_1 - M_2 \frac{l_1}{l_2} = 0.25 \cdot 10^6 \text{ Nmm}$$

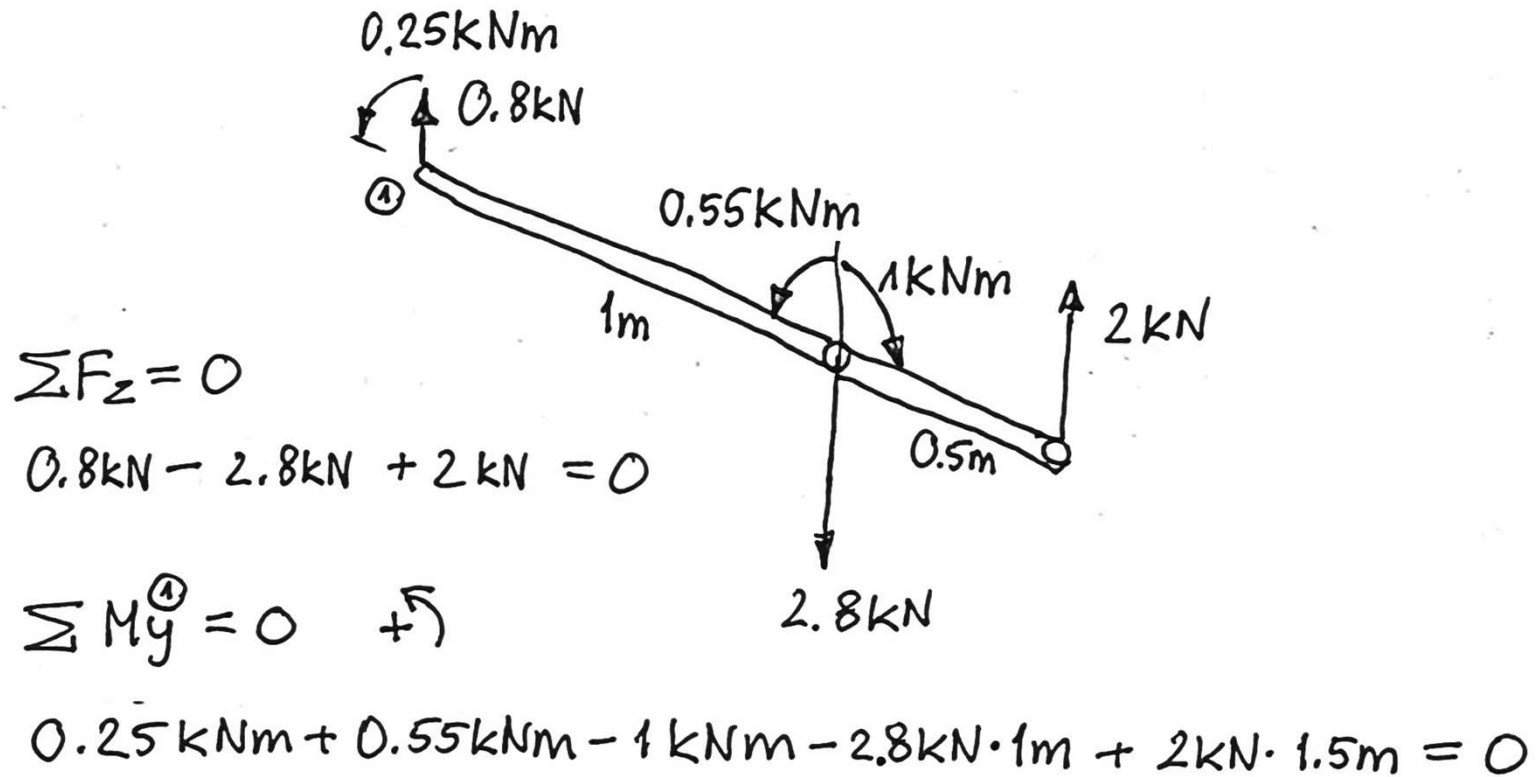
$$\begin{aligned}
 R_6 &= -\frac{12EIy_2}{l_2^3} \cdot q_3 + 0 \cdot q_4 - \frac{6EIy_2}{l_2^2} \cdot q_5 - \frac{6EIy_2}{l_2^2} \cdot q_7 = \\
 &= -\frac{12EIy_2}{l_2^3} \cdot \frac{\left(\frac{3}{2} \frac{M_1}{l_1} + \frac{M_2}{l_2} - F\right) l_1^3}{3EIy_1} + \\
 &\quad - \frac{6EIy_2}{l_2^2} \cdot \left( -\frac{M_2 l_2 + \frac{J_{y2}}{J_{y1}} \frac{l_1^3}{l_2} \left(\frac{3}{2} \frac{M_1}{l_1} + \frac{M_2}{l_2} - F\right)}{3EIy_2} \right) + \\
 &\quad - \frac{6EIy_2}{l_2^2} \cdot \left( \frac{\frac{1}{2} M_2 l_2 - \frac{J_{y2}}{J_{y1}} \frac{l_1^3}{l_2} \left(\frac{3}{2} \frac{M_1}{l_1} + \frac{M_2}{l_2} - F\right)}{3EIy_2} \right) =
 \end{aligned}$$

$$= -4 \frac{J_{y2}}{J_{y1}} \frac{l_1^3}{l_2^3} \left(\frac{3}{2} \frac{M_1}{l_1} + \frac{M_2}{l_2} - F\right) +$$

$$+ 2 \left(\frac{M_2}{l_2} + \frac{J_{y2}}{J_{y1}} \frac{l_1^3}{l_2^3} \left(\frac{3}{2} \frac{M_1}{l_1} + \frac{M_2}{l_2} - F\right)\right) +$$

$$- 2 \left(\frac{1}{2} \frac{M_2}{l_2} - \frac{J_{y2}}{J_{y1}} \frac{l_1^3}{l_2^3} \left(\frac{3}{2} \frac{M_1}{l_1} + \frac{M_2}{l_2} - F\right)\right) = \frac{M_2}{l_2} = 2000 \text{ N}$$

## EQUILIBRIUM CHECK



## ELEMENT SOLUTION

### DEFLECTION

[1]

$$w_1(\xi_1) = \underset{1 \times 4}{[N]} \cdot \underset{4 \times 1}{\begin{Bmatrix} q_1 \\ q_2 \\ q_3 \\ q_4 \end{Bmatrix}} = [N_1, N_2, N_3, N_4] \cdot \begin{Bmatrix} 0 \\ 0 \\ q_3 \\ q_4 \end{Bmatrix} =$$

$$= N_3 \cdot q_3 + N_4 \cdot q_4 =$$

$$= \left( \frac{3}{l_1^2} \cdot \xi_1^2 - \frac{2}{l_1^3} \cdot \xi_1^3 \right) \cdot q_3 + \left( \frac{1}{l_1^2} \cdot \xi_1^3 - \frac{1}{l_1} \cdot \xi_1^2 \right) q_4$$

$$w_1(0) = 0, \quad w_1(l_1) = (3-2)q_3 + (1-1)q_4 = q_3$$

$$\frac{dw_1}{d\xi_1} = \left( \frac{6}{l_1^2} \xi_1 - \frac{6}{l_1^3} \xi_1^2 \right) q_3 + \left( \frac{3}{l_1^2} \xi_1^2 - \frac{2}{l_1} \xi_1 \right) q_4$$

$$\left. \frac{dw_1}{d\xi_1} \right|_{625\text{mm}} = 0 \Rightarrow w_{1\min} = w_1(625) = -0.712\text{mm}$$



## BENDING MOMENT

$$\begin{aligned} M_{y_1}(\xi_1) &= w_1'' E J_{y_1} = E J_{y_1} \cdot (N_3'' \cdot q_3 + N_4'' \cdot q_4) = \\ &= E J_{y_1} \cdot \left( \left( \frac{6}{l_1^2} - \frac{12}{l_1^3} \xi_1 \right) \cdot q_3 + \left( \frac{6}{l_1^2} \xi_1 - \frac{2}{l_1} \right) q_4 \right) \end{aligned}$$

$$M_{y_1}(0) = -0.25 \cdot 10^6 \text{ Nmm}$$

$$M_{y_1}(l_1) = 0.55 \cdot 10^6 \text{ Nmm} = M_1$$

## SHEAR FORCE

$$\begin{aligned} T_{z_1}(\xi_1) &= -w_1''' E J_{y_1} = -E J_{y_1} (N_3''' \cdot q_3 + N_4''' \cdot q_4) = \\ &= +E J_{y_1} \cdot \left( \frac{12}{l_1^3} q_3 - \frac{6}{l_1^2} q_4 \right) = -800 \text{ N} \end{aligned}$$

2

DEFLECTION

$$w_2(\xi_2) = \underline{N} \cdot \{q\}_2 = \underline{N}_{1,2,3,4} \cdot \begin{Bmatrix} q_3 \\ q_5 \\ 0 \\ q_7 \end{Bmatrix} =$$

$$= N_1 \cdot q_3 + N_2 \cdot q_5 + N_4 \cdot q_7 =$$

$$= \left(1 - \frac{3}{l_2^2} \xi_2^2 + \frac{2}{l_2^3} \xi_2^3\right) q_3 + \left(\xi_2 - \frac{2}{l_2} \xi_2^2 + \frac{1}{l_2^2} \xi_2^3\right) q_5 + \left(\frac{1}{l_2^2} \xi_2^3 - \frac{1}{l_2} \xi_2^2\right) q_7$$

$$w_2(0) = q_3$$

$$w_2(l_2) = (1 - 3 + 2) q_3 + (l_2 - 2l_2 + l_2) q_5 + (l_2 - l_2) q_7 = 0$$

$$\frac{dw_2}{d\xi_2} = \left(\frac{6}{l_2^3} \xi_2^2 - \frac{6}{l_2^2} \xi_2\right) q_3 + \left(1 - \frac{4}{l_2} \xi_2 + \frac{3}{l_2^2} \xi_2^2\right) q_5 + \left(\frac{3}{l_2^2} \xi_2^2 - \frac{2}{l_2} \xi_2\right) q_7$$

$$\left. \frac{dw_2}{d\xi_2} \right|_{255.7 \text{ mm}} = 0 \Rightarrow w_{2 \min} = w_2(255.7) = -0.3 \text{ mm}$$

## BENDING MOMENT

$$\begin{aligned} M_{y_2}(\xi_2) &= w_2'' E J_{y_2} = E J_{y_2} (N_1'' \cdot q_3 + N_2'' \cdot q_5 + N_4'' \cdot q_7) = \\ &= E J_{y_2} \cdot \left( \left( \frac{12}{l_2^3} \xi_2 - \frac{6}{l_2^2} \right) q_3 + \left( \frac{6}{l_2^2} \xi_2 - \frac{4}{l_2} \right) q_5 + \left( \frac{6}{l_2^2} \xi_2 - \frac{2}{l_2} \right) q_7 \right) \end{aligned}$$

$$M_{y_2}(0) = 1 \cdot 10^6 \text{ Nmm} = M_2$$

$$M_{y_2}(l_2) = 0$$

## SHEAR FORCE

$$\begin{aligned} T_{z_2} &= -w_2''' \cdot E J_{y_2} = -E J_{y_2} \cdot (N_1''' \cdot q_3 + N_2''' \cdot q_5 + N_4''' \cdot q_7) = \\ &= -E J_{y_2} \cdot \left( \frac{12}{l_2^3} q_3 + \frac{6}{l_2^2} q_5 + \frac{6}{l_2^2} q_7 \right) = 2000 \text{ N} \end{aligned}$$

# DEFORMATION AND INTERNAL FORCES

